You are **NOT** allowed to use any type of calculators.

$1 \quad (8+10=18 \text{ pts})$

Inner product spaces

(a) Let V be an inner product space. Find real numbers a and b such that the so-called Apollonius' identity

$$||z - x||^{2} + ||z - y||^{2} = a||x - y||^{2} + b||z - \frac{x + y}{2}||^{2}$$

holds for any triple x, y, and z in V.

(b) Consider the vector space C[-1, 1] with the inner product

$$\langle f,g \rangle = \int_{-1}^{1} f(x)g(x) \, dx.$$

Find the best approximation of the constant function 1 within the subspace spanned by the vectors x and |x|.

REQUIRED KNOWLEDGE: inner product, Gram-Schmidt process

SOLUTION:

(1a):

The left hand side can be written as

$$2\langle z,z\rangle + \langle x,x\rangle + \langle y,y\rangle - \langle x,z\rangle - \langle z,x\rangle - \langle y,z\rangle - \langle z,y\rangle$$

In addition the right hand side is

$$\begin{aligned} a(\langle x,x\rangle + \langle y,y\rangle - \langle x,y\rangle - \langle y,x\rangle) + b(\langle z,z\rangle + \langle \frac{x+y}{2}, \frac{x+y}{2}\rangle - \langle z, \frac{x+y}{2}\rangle - \langle \frac{x+y}{2},z\rangle) \\ &= b\langle z,z\rangle + \left(\frac{1}{4}b+a\right)(\langle x,x\rangle + \langle y,y\rangle) + \left(\frac{1}{4}b-a\right)(\langle x,y\rangle + \langle y,x\rangle) - \frac{1}{2}b(\langle z,x\rangle + \langle x,z\rangle + \langle z,y\rangle + \langle y,z\rangle) . \end{aligned}$$

We get that the following should hold:

$$b = 2
 \frac{1}{4}b + a = 2
 \frac{1}{4}b - a = 0
 \frac{1}{2}b = 2$$

which only hold for $a = \frac{1}{2}$ and b = 2.

Remark. In real inner product space the left hand side is

$$2\langle z,z\rangle + \langle x,x\rangle + \langle y,y\rangle - 2\langle x,z\rangle - 2\langle y,z\rangle$$

and the right hand side is

$$=b\langle z,z\rangle+\left(\frac{1}{4}b+a\right)\left(\langle x,x\rangle+\langle y,y\rangle\right)+\left(\frac{1}{2}b-2a\right)\left(\langle x,y\rangle\right)-b\left(\langle z,x\rangle+\langle z,y\rangle\right)$$

(1b): Note that

$$\langle x, |x| \rangle = 0.$$

As such, these two vectors are orthogonal. In order to obtain an orthonormal basis, we first compute the norms:

$$||x||^{2} = ||x|||^{2} = \int_{-1}^{1} x^{2} dx = \frac{x^{3}}{3}|_{-1}^{1} = \frac{2}{3}.$$

Therefore, the vectors $\frac{\sqrt{3}}{\sqrt{2}}x$ and $\frac{\sqrt{3}}{\sqrt{2}}|x|$ form an orthonormal basis. So, the best approximation of the constant function 1 within the mentioned subspace can be found as:

$$p = \langle 1, \frac{\sqrt{3}}{\sqrt{2}}x \rangle \frac{\sqrt{3}}{\sqrt{2}}x + \langle 1, \frac{\sqrt{3}}{\sqrt{2}}|x| \rangle \frac{\sqrt{3}}{\sqrt{2}}|x| = \frac{3}{2}\langle 1, x \rangle x + \frac{3}{2}\langle 1, |x| \rangle |x| = \frac{3}{2}|x|.$$

Consider the matrix

$$M = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & -1 \\ -1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}.$$

(a) Find a singular value decomposition for M.

(b) Find the best rank 2 approximation of M.

REQUIRED KNOWLEDGE: singular value decomposition, lower rank approximations

SOLUTION:

(2a): Note that

$$M^T M = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}.$$

As such, we obtain

$$\sigma_1 = \sigma_2 = \sigma_3 = \sqrt{3}.$$

 $\overline{}$

This mans that

$$\Sigma = \begin{bmatrix} \sqrt{3} & 0 & 0\\ 0 & \sqrt{3} & 0\\ 0 & 0 & \sqrt{3}\\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad V = \begin{bmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{bmatrix}$$

By using the formula

$$u_i = \frac{1}{\sigma_i} M v_i$$

for i = 1, 2, 3, we get

$$u_{1} = \frac{1}{\sqrt{3}} \begin{bmatrix} 1\\1\\-1\\0 \end{bmatrix} \quad u_{2} = \frac{1}{\sqrt{3}} \begin{bmatrix} 0\\1\\1\\1 \end{bmatrix} \quad u_{3} = \frac{1}{\sqrt{3}} \begin{bmatrix} 1\\-1\\0\\1 \end{bmatrix}.$$

By solving $M^T u_4 = 0$, we obtain

$$u_4 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1\\0\\1\\-1 \end{bmatrix}.$$

Thus, a singular value decomposition can be given by

$$M = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 0 & 1 & 1\\ 1 & 1 & -1 & 0\\ -1 & 1 & 0 & 1\\ 0 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} \sqrt{3} & 0 & 0\\ 0 & \sqrt{3} & 0\\ 0 & 0 & \sqrt{3} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{bmatrix}.$$

(2b): One such approximation can be found as

$$\frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 0 & 1 & 1\\ 1 & 1 & -1 & 0\\ -1 & 1 & 0 & 1\\ 0 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} \sqrt{3} & 0 & 0\\ 0 & \sqrt{3} & 0\\ 0 & 0 & 0\\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0\\ 1 & 1 & 0\\ -1 & 1 & 0\\ 0 & 1 & 0 \end{bmatrix}.$$

Suppose that a matrix has the characteristic polynomial

$$p(\lambda) = \lambda(\lambda + 2)(\lambda^2 + 1).$$

Prove that this matrix is

(a) singular.

- (b) diagonalizable.
- (c) NOT symmetric.
- (d) NOT skew-symmetric.
- (e) NOT orthogonal.

REQUIRED KNOWLEDGE: eigenvalues/vectors, diagonalizability, (skew-)symmetric matrices, orthogonal matrices.

SOLUTION:

(3a): From the characteristic polynomial we can deduce that the eigenvalues of the matrix are 0, -2, i and -i. Since 0 is an eigenvalue, the matrix is singular.

(3b): Since the matrix has distinct eigenvalues, it is diagonalizable.

(3c): A symmetric matrix has real eigenvalues. Since this matrix has as i and -i among its eigenvalues, the matrix can not be symmetric.

(3d): Suppose that a matrix A is skew-symmetric and let λ be an eigenvalue of A with a corresponding eigenvector x. In general, we have

$$x^*Ax = x^*\lambda x = \lambda ||x||^2$$
$$x^*A^Tx = (A\bar{x})^Tx = \bar{\lambda} ||x||^2.$$

Since a skew-symmetric matrix satisfies $A^T = -A$, it follows that

$$\bar{\lambda} \|x\|^2 = x^* A^T x = -x^* A x = -\lambda \|x\|^2$$

Hence, $\bar{\lambda} = -\lambda$, so $\operatorname{Re}(\lambda) = 0$. It follows that all eigenvalues of a skew-symmetric matrix are purely imaginary. Since the matrix in question has -2 among its eigenvalues, it can not be skew-symmetric.

Alternatively, if λ is an eigenvalue of A it is also an eigenvalue of A^T . If the matrix A is skew-symmetric, we have $A^T = -A$, and hence λ is also an eigenvalue of -A. Consequently, $-\lambda$ is an eigenvalue of A. So we see that if λ is an eigenvalue of a skew-symmetric matrix, then $-\lambda$ is as well. The matrix in question has -2 as one of its eigenvalues, but 2 is not one of its eigenvalues. Hence, the matrix is not skew-symmetric.

(3e): An orthogonal matrix is non-singular. Since this matrix is singular, it can not be orthogonal.

Alternatively, every eigenvalue λ of an orthogonal matrix satisfies $|\lambda| = 1$. The matrix in question has 0 and -2 as eigenvalues, which do not satisfy this condition, hence the matrix is not orthogonal.

Let a be a real number. Determine all values of a such that the matrix

$$\begin{bmatrix} 1 & a & 1 \\ a & a & a+1 \\ 1 & a+1 & 1 \end{bmatrix}$$

is

- (a) positive definite.
- (b) negative definite.

REQUIRED KNOWLEDGE: Positive definite matrices, the principal minor test.

SOLUTION:

(4a): A symmetric matrix is positive definite if and only if all its principal minors are positive. Note that

$$\det(1) = 1 \qquad \det(\begin{bmatrix} 1 & a \\ a & a \end{bmatrix}) = a - a^2 \qquad \det(\begin{bmatrix} 1 & a & 1 \\ a & a & a + 1 \\ 1 & a + 1 & 1 \end{bmatrix}) = a + 2a(a+1) - a - a^2 - (a+1)^2 = -1.$$

Therefore, this matrix cannot be positive definite for any values of a

(4b): A symmetric matrix M is negative definite definite if and only if -M is positive definite. Hence, we can apply the minor test for the negative of the matrix. Note that

$$\det(-1) = -1.$$

As such, this matrix is never negative definite.

Consider the matrix

$$\begin{bmatrix} 2 & 2 & 0 & -1 \\ 0 & 0 & 0 & 1 \\ 1 & 5 & 2 & -1 \\ 0 & -4 & 0 & 4 \end{bmatrix}.$$

- (a) Show that the characteristic polynomial is $p(\lambda) = (\lambda 2)^4$.
- (b) Is it diagonalizable? Why?
- (c) Put it into the Jordan canonical form.

REQUIRED KNOWLEDGE: diagonalization, Jordan canonical form.

SOLUTION:

(5a): Note that

$$\det\left(\begin{bmatrix} 2-\lambda & 2 & 0 & -1\\ 0 & -\lambda & 0 & 1\\ 1 & 5 & 2-\lambda & -1\\ 0 & -4 & 0 & 4-\lambda \end{bmatrix}\right) = (2-\lambda)\det\left(\begin{bmatrix} 2-\lambda & 2 & -1\\ 0 & -\lambda & 1\\ 0 & -4 & 4-\lambda \end{bmatrix}\right)$$
$$= (2-\lambda)^2 \det\left(\begin{bmatrix} -\lambda & 1\\ -4 & 4-\lambda \end{bmatrix}\right)$$
$$= (2-\lambda)^2(-4\lambda + \lambda^2 + 4) = (2-\lambda)^4.$$

(5b): To compute eigenvalues, we need to solve the linear equations

$$\begin{bmatrix} 0 & 2 & 0 & -1 \\ 0 & -2 & 0 & 1 \\ 1 & 5 & 0 & -1 \\ 0 & -4 & 0 & 2 \end{bmatrix} x = 0.$$

This is equivalent to

$$\begin{bmatrix} 1 & 5 & 0 & -1 \\ 0 & 2 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} x = 0$$

Thus, there are two linearly independent eigenvectors, for instance

$$x_1 = \begin{bmatrix} 0\\0\\1\\0 \end{bmatrix} \quad \text{and} \quad x_2 = \begin{bmatrix} -3\\1\\0\\2 \end{bmatrix}.$$

Consequently, diagonalization is impossible.

(5c): Note that

Now, we try to solve one of the following line equations

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -2 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} y = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \quad \text{or} \quad \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -2 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} y = \begin{bmatrix} -3 \\ 1 \\ 0 \\ 2 \end{bmatrix}$$

Clearly the latter has no solution whereas

$$y = \begin{bmatrix} 0\\0\\0\\\frac{1}{2} \end{bmatrix}$$

solves the former. Thus, we have

$$\begin{bmatrix} 0\\0\\0\\\frac{1}{2}\\\frac{1}{2} \end{bmatrix}, \begin{bmatrix} 0&2&0&-1\\0&-2&0&1\\1&5&0&-1\\0&-4&0&2 \end{bmatrix} \begin{bmatrix} 0\\0\\\frac{1}{2}\\\frac{1$$

as a Jordan chain. Thus, we get

$\begin{bmatrix} 2 \\ 0 \end{bmatrix}$	2	0	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	$-\frac{1}{2}{1}$	0	$\begin{bmatrix} -3 \\ 1 \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	$-\frac{1}{2}{1}$	0	$\begin{bmatrix} -3 \\ 1 \end{bmatrix}$	$\begin{bmatrix} 2 \\ 0 \end{bmatrix}$	1	0	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	
$\begin{vmatrix} 0\\ 1 \end{vmatrix}$	$\frac{1}{5}$	$\frac{0}{2}$	$\begin{bmatrix} 1 \\ -1 \end{bmatrix}$	$\begin{vmatrix} 0\\ 1 \end{vmatrix}$	$-\frac{1}{2}$	0	$\begin{bmatrix} 1\\0 \end{bmatrix} =$	$= \begin{bmatrix} 0\\1 \end{bmatrix}$	$-\frac{1}{2}$	0	$\begin{bmatrix} 1\\0 \end{bmatrix}$	0	$\frac{2}{0}$	$\frac{1}{2}$	$\begin{bmatrix} 0\\0 \end{bmatrix}$	
0	-4	0	4	0	1	$\frac{1}{2}$	2	0	1	$\frac{1}{2}$	2	0	0	0	2	